

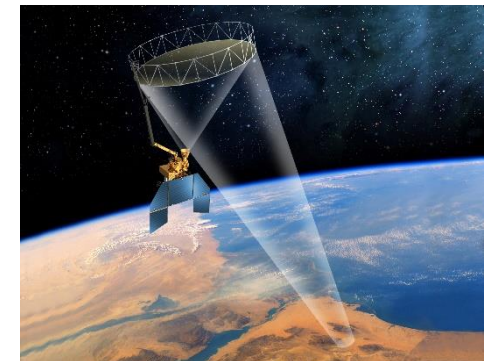
Potential of satellite surface soil moisture products for spatially calibrating distributed eco-hydrological models

José Gomis-Cebolla, Alicia Garcia-Arias, Martí Perpinyà-Vallès, **Félix Francés**

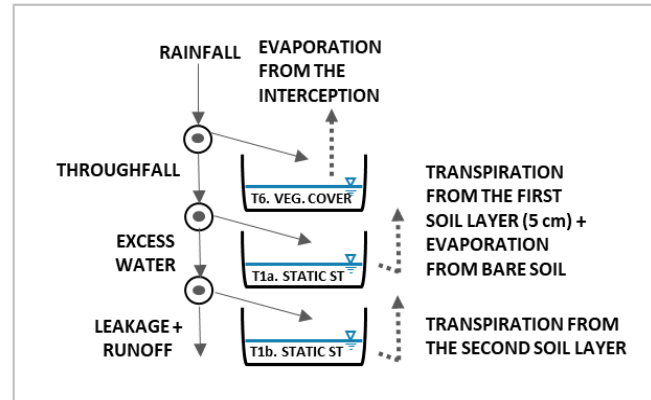
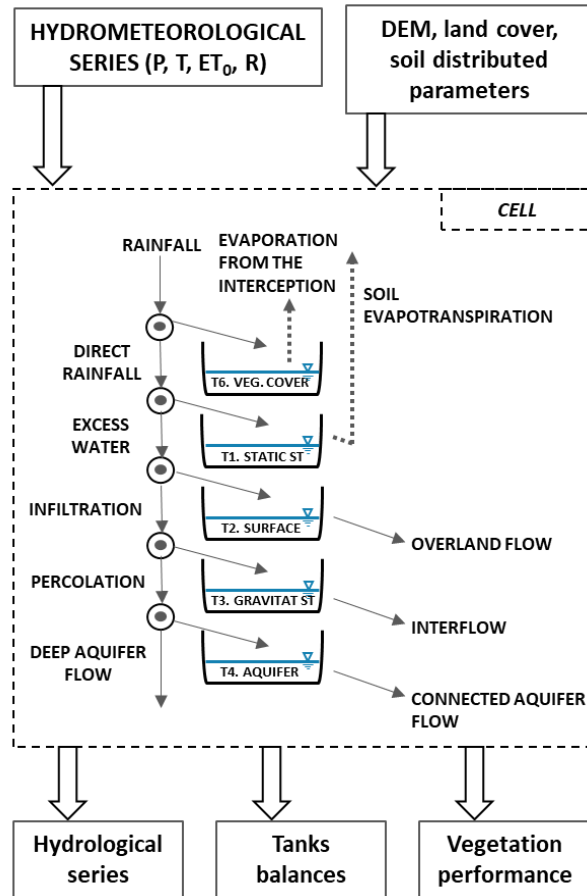
Research Group of Hydrological and Environmental Modelling (GIMHA)



- ❑ Distributed eco-hydrological models (DEHM) can provide spatial description of hydrological processes
- ❑ Satellite information can be used for the spatial calibration of DEHM (*Ruiz-Pérez et al., 2017; Echeverría et al., 2019*)
- ❑ Sentinel-1, SMAP and SMOS surface soil moisture (SSM) products are available at 1km. However, they are not free from errors
- ❑ Research questions:
 - **How well do SSM products agree with DEHM?**
 - **Could they be useful for DEHM calibration?**



Hydrological sub-model



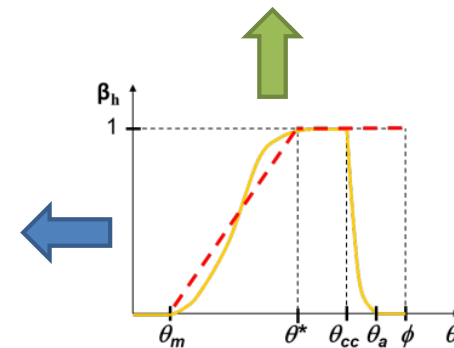
Hydrological Correction factors	
FC1 - Maximum Static storage	
FC2 - Vegetation factor evapotranspiration	
FC3 - Infiltration capacity	
FC4 - Slope velocity	
FC5 - Percolation capacity	
FC6 - Interflow hydraulic capacity	
FC7 - Deep aquifer percolation capacity	
FC8 - Connected aquifer hydraulic conductivity	
FC9 - Kinematic Geomorphological Wave	

Dynamic vegetation sub-model

$$\frac{dB_l}{dt} = (LUE \cdot \varepsilon \cdot PAR \cdot fPAR - Re) \cdot \varphi_l(B_l) - k_l B_l$$

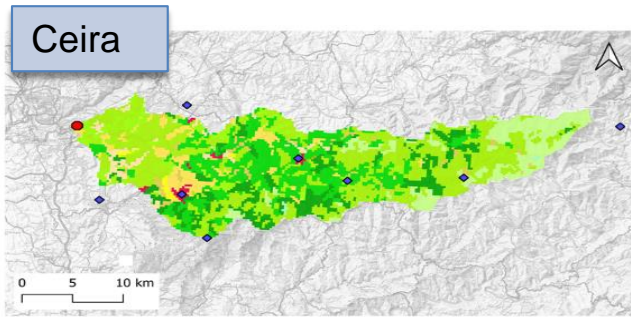
- ✓ State variable: leaf biomass
- ✓ Based on LUE

Vegetation Parameters	
β (-)	Exponent in the soil water limitation function
ξ (-)	Exponent in the vegetation water stress function
lmax (mm)	Maximum leaf interception storage
Rd (%)	Root distribution
k _l (-)	Light extinction coefficient
T _{opt} (°C)	Optimum temperature
LUE (gC/MJd)	Light Use Efficiency
rr (gC/gN d)	Respiration rate
k _d (-)	Leaf natural decay factor
SLA (m ² /gC)	Specific leaf area
LAI _{max} (m ² /m ²)	Maximum LAI



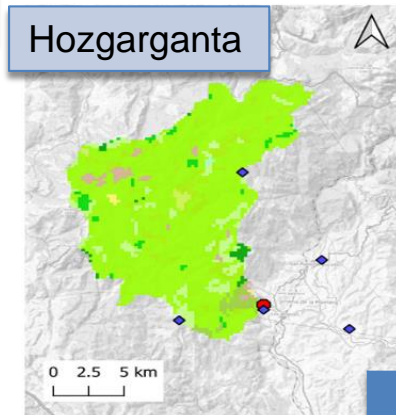
- ✓ ε : stress factor including water
- ✓ T_i = ET₀ · f_c · min(1, LAI) · β(H_i)

- ✓ Representative of the climatology and hydrology of the Mediterranean Bio-geographical in the Iberian Peninsula



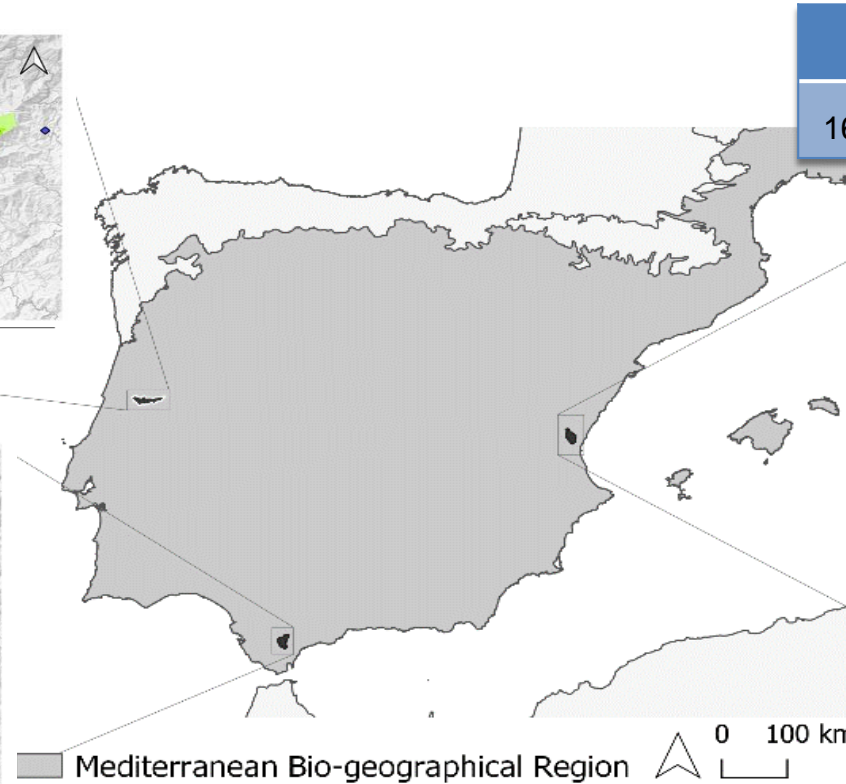
- 496.89 km²
- 62-1380 m.a.s.l
- Forestry
- Dense vegetation +

T (°C)	P (mm)	ETO (mm)
14.0 ± 0.3	706 ± 328	412 ± 3

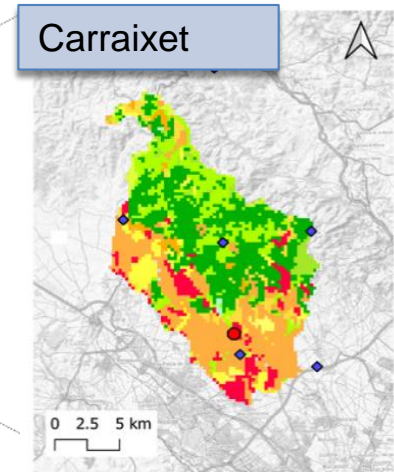


- 228.3 km²
- 38-1042 m.a.s.l
- Forestry
- Dense vegetated +++

T (°C)	P (mm)	ETO (mm)
17.7±0.4	826 ± 278	1212 ± 41



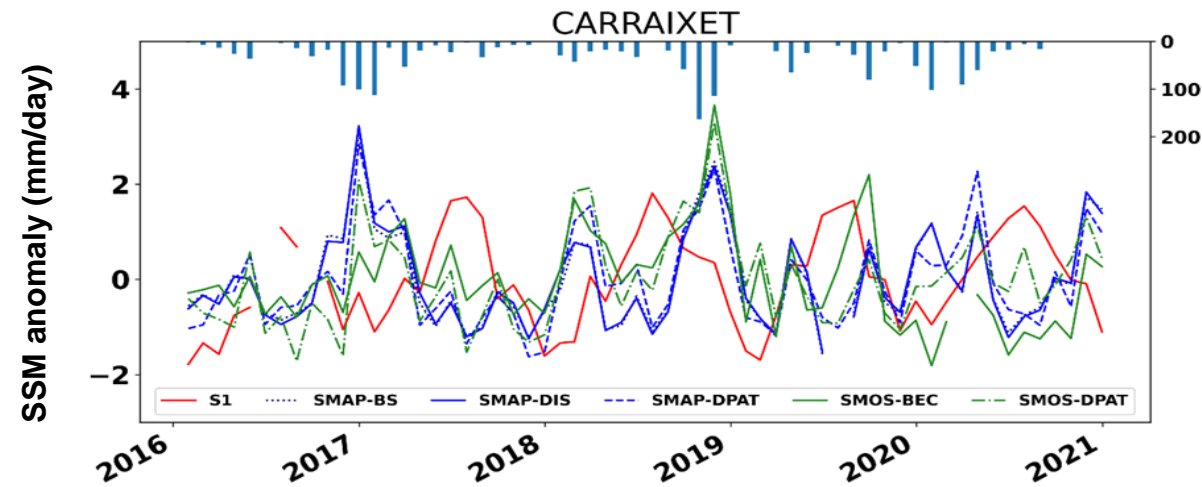
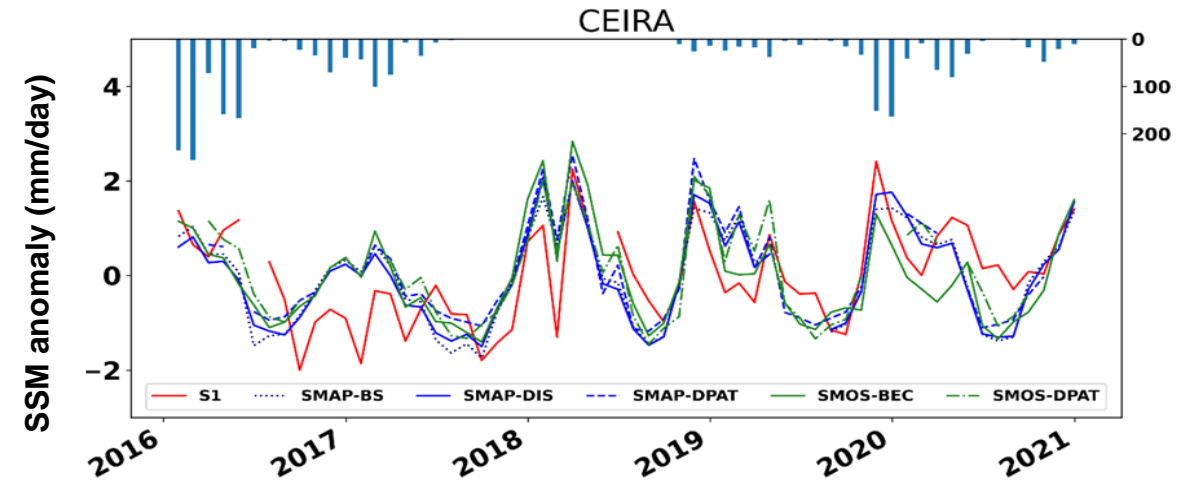
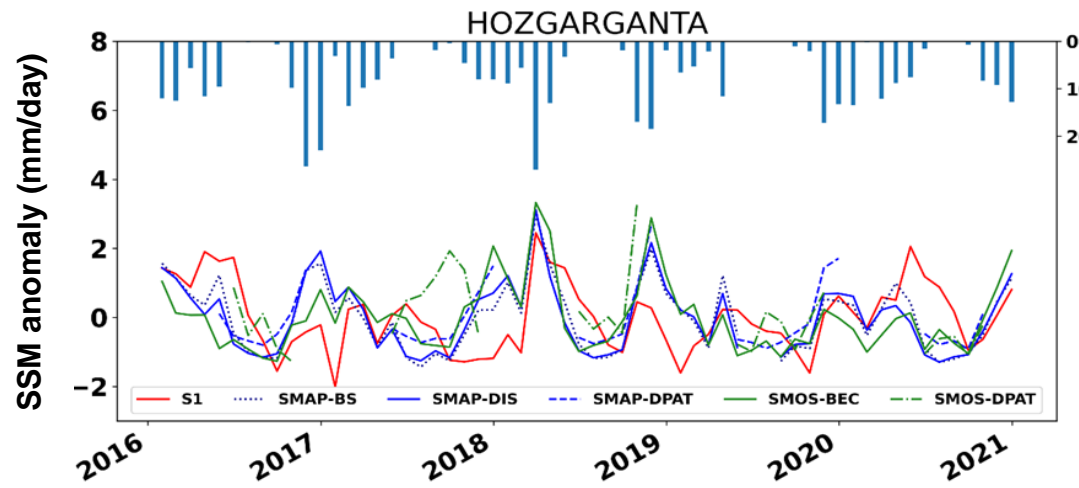
T (°C)	P (mm)	ETO (mm)
16.6 ± 0.1	373 ± 108	1142 ± 11

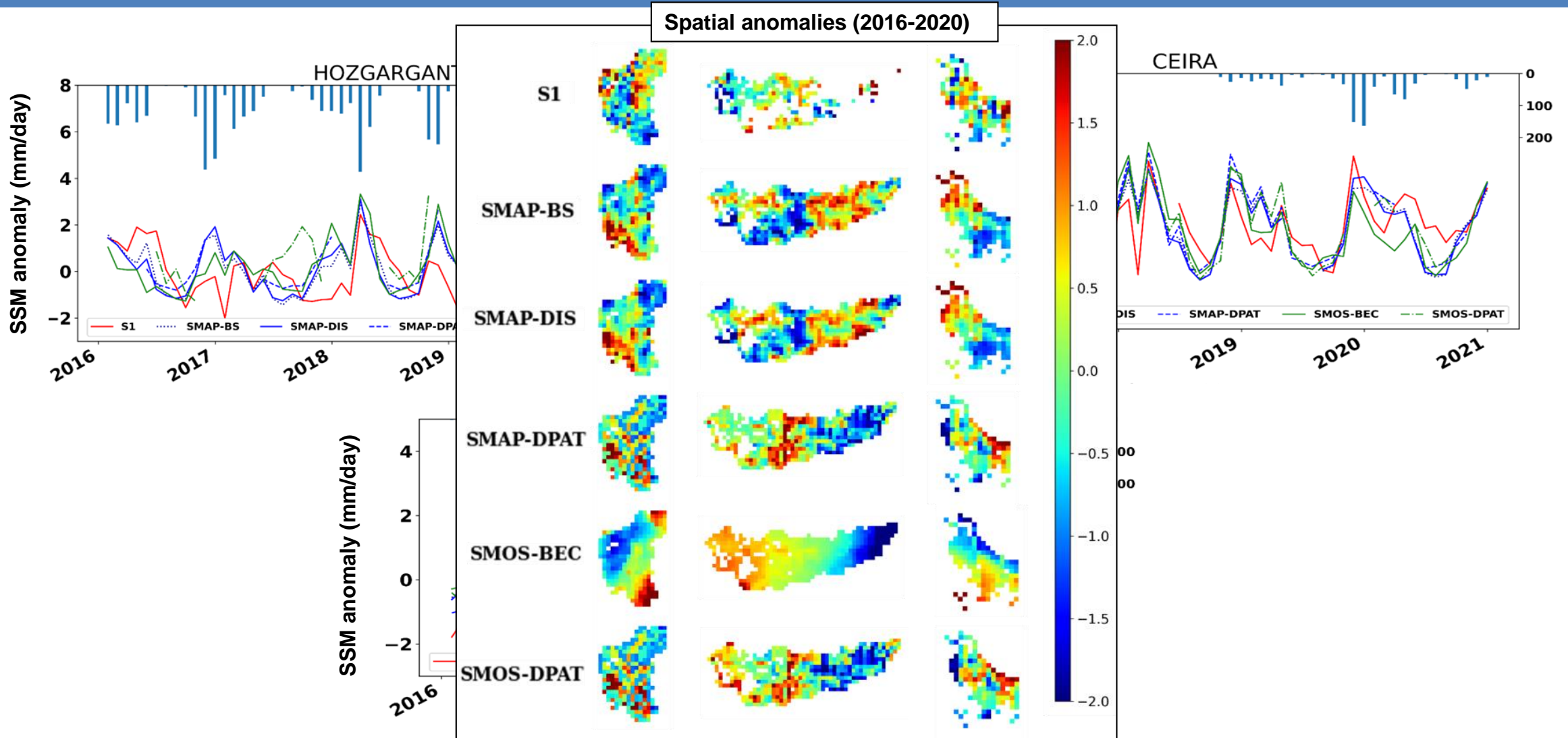


- 236.5 km²
- 55-898 m.a.s.l
- Forestry and agricultural
- Dense vegetation +
- Ephemeral river

SSM is for first 5cm!

	Band	Spatial resolution	Retrieval method
Sentinel-1 (S1)	C	1 km	TU-Wien change detection method (Wagner, 1998)
SMAP/S1 (SMAP-BS & SMAP-DIS)	L+C	1 km	Passive (SMAP) + active (Sentinel-1) downscaling (Das et al., 2017)
SMOS-BEC	L	1 km	SMOS disaggregation using LST and NDVI (Piles et al., 2011-2012).
SMAP-Dispatch (SMAP-DPAT)	L	1 km	SMAP and SMOS disaggregation of SSM using the soil evaporative efficiency (SEE). LST and NDVI are used as inputs (Merlin et al., 2013).
SMOS-Dispatch (SMOS-DPAT)	L	1 km	





EUDEM + CORINE LAND COVER + 3D-EUROSOILS + GLHYMPS + SOILSGRIDS + LANDSAT + SiAR + SAIH-HIDROSUR + SAIH-JUCAR+SNIRH

TETIS

Sobol Sensitivity analysis

Sensitive parameters + calibration ranges

Multi-objective/variable calibration + validation

OF for Q:

$$NSE = 1 - \frac{\sum_{i=1}^n (Q_{si} - Q_{oi})^2}{\sum_{i=1}^n (Q_{oi} - \bar{Q}_o)^2}$$

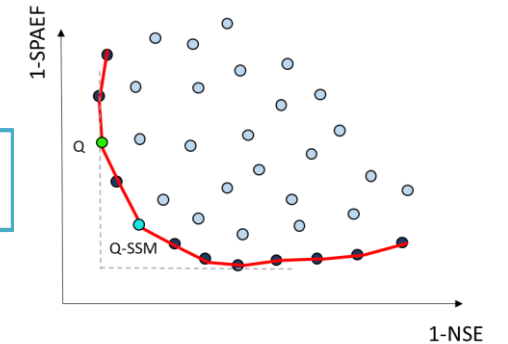


OF for satellite SSM:

$$SPAEF = 1 - \sqrt{(\alpha - 1)^2 + (\beta - 1)^2 + (\gamma - 1)^2}$$

$$\alpha = \rho(\text{obs, sim}), \beta = \left(\frac{\sigma_{\text{sim}}}{\mu_{\text{sim}}}\right) / \left(\frac{\sigma_{\text{obs}}}{\mu_{\text{obs}}}\right) \text{ and } \gamma = \frac{\sum_{j=1}^n \min(K_j, L_j)}{\sum_{j=1}^n K_j}$$

MOSCEM-UA
(Vrugt et al. 2003)



- ✓ Hoz+Carraixet: 2016-2017 (CAL) + 2018-2019 (VAL)
- ✓ Ceira: 08-2015/07-2017 (CAL) + 03-2019/07-2020 (VAL)
- ✓ NSE (1day) + SPAEF (1month)
- ✓ TETIS is run in natural mode (250 m)

- ✓ Optimum point: minimum Euclidean distance to the reference point

EUDEM + CORINE LAND COVER + 3D-EUROSOILS + GLHYMPS + SOILSGRIDS + LANDSAT + SiAR + SAIH-HIDROSUR + SAIH-JUCAR+SNIRH

TETIS

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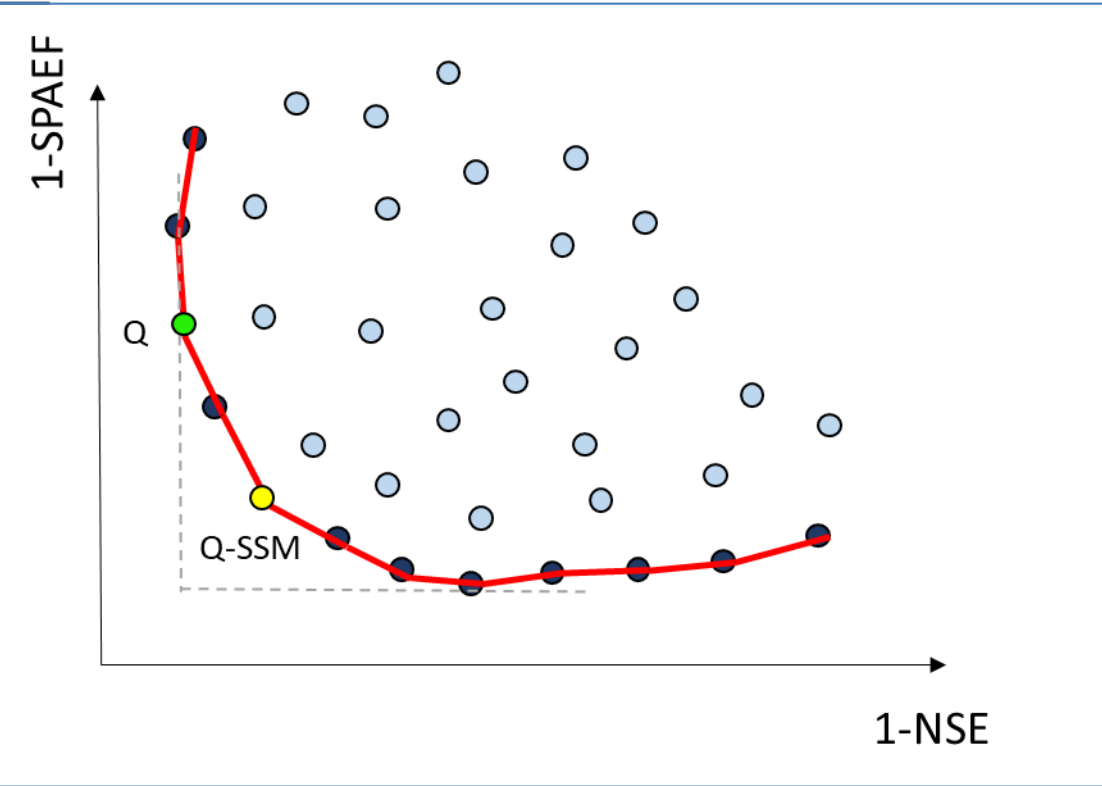
$$NSE = 1 - \frac{\sum_{i=1}^n (Q_{si} - Q_{oi})^2}{\sum_{i=1}^n (Q_{oi} - \bar{Q}_o)^2}$$



OF for satellite SSM:

$$SPAEF = 1 - \sqrt{(\alpha - 1)^2 + (\beta - 1)^2 + (\gamma - 1)^2}$$

$$\alpha = \rho(\text{obs, sim}), \beta = \left(\frac{\sigma_{\text{sim}}}{\mu_{\text{sim}}}\right) / \left(\frac{\sigma_{\text{obs}}}{\mu_{\text{obs}}}\right) \text{ and } \gamma = \frac{\sum_{j=1}^n \min(\mu_{\text{sim}}, \mu_{\text{obs}})}{\sum_{j=1}^n \mu_{\text{obs}}}$$



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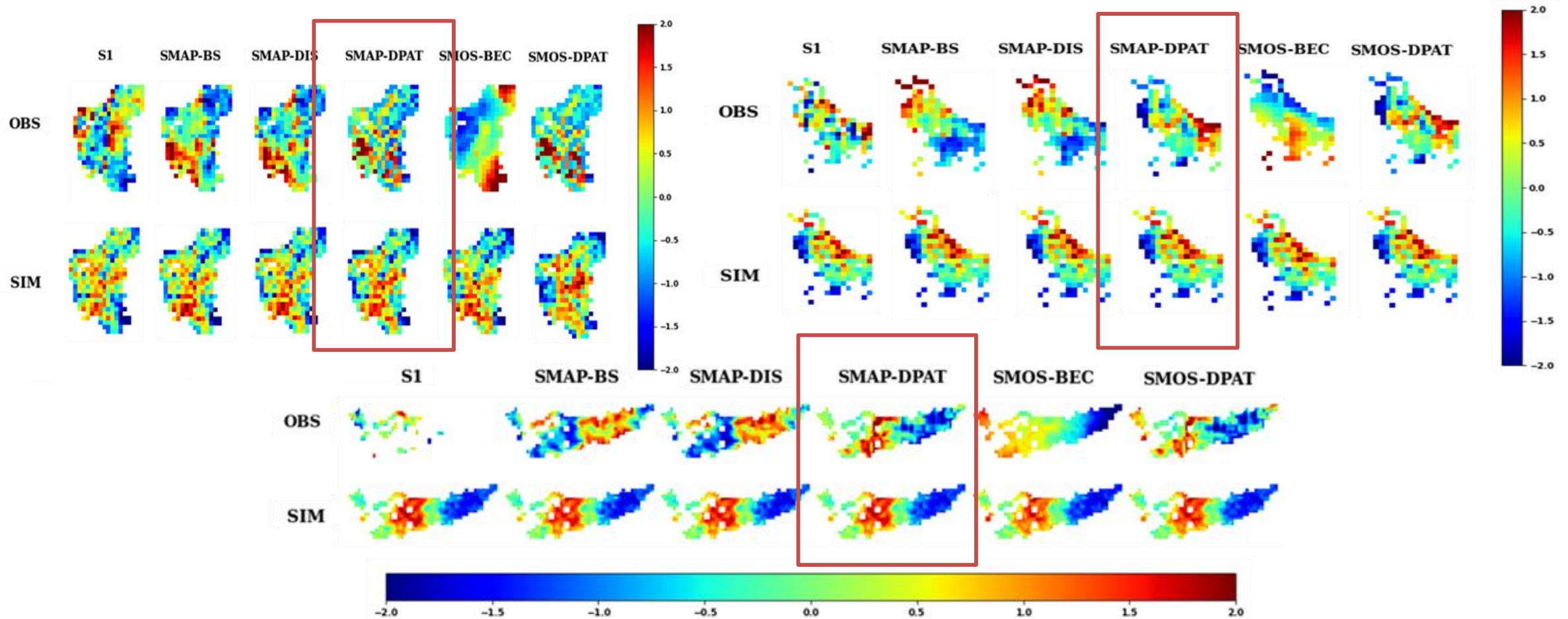
CALIBRATION

	HOZ			CEI			CAR		
	NSE	SPAEF	R	NSE	SPAEF	R	NSE	SPAEF	R
S1	++	-	-	+++	++	-	++	+++	-
SMAP-DIS	+++	-	+++	+++	-	+++	++	+	+++
SMAP-BS	+++	+	++	+++	-	+	++	+	+++
SMAP-DPAT	+++	+	+++	++	+	+++	++	+++	+++
SMOS-BEC	+++	-	++	++	++	+++	+++	-	+
SMOS-DPAT	+++	+	-	++	++	+++	++	+++	++

VALIDATION

	HOZ			CEI			CAR		
	NSE	SPAEF	R	NSE	SPAEF	R	NSE	SPAEF	R
S1	+	-	-	+	+	++	++	+++	-
SMAP-DIS	+++	-	+++	++	-	+++	+	+	+++
SMAP-BS	++	+	++	+	-	++	++	++	+++
SMAP-DPAT	++	+	++	++	+++	+++	+	+++	+++
SMOS-BEC	+	+	+++	+	+	++	++	-	++
SMOS-DPAT	++	-	+	++	+++	++	+	+++	++

Spatial anomalies Validation

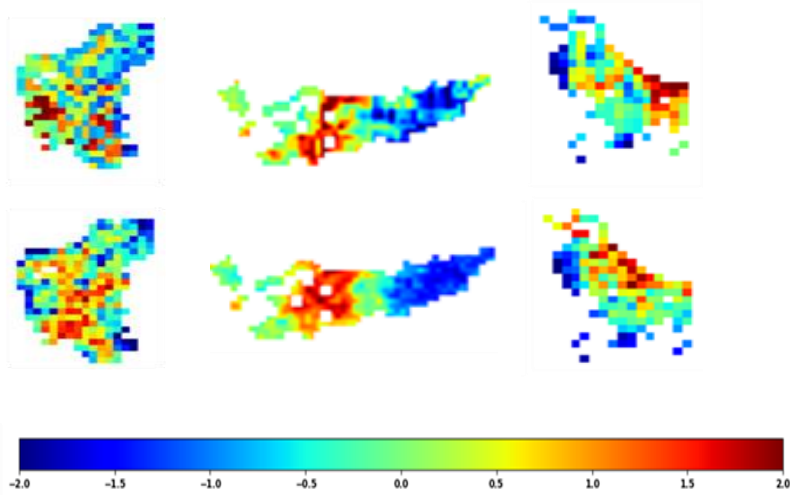


Spatial anomalies

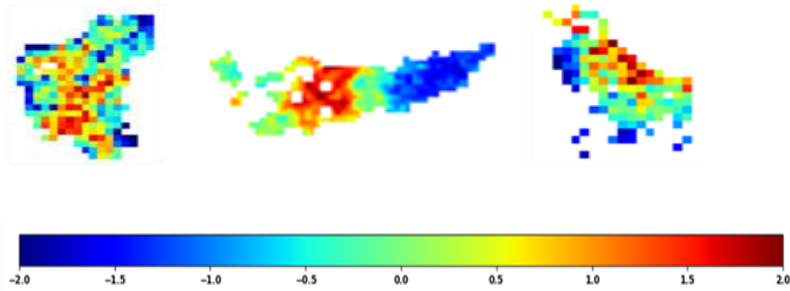
CALIBRATION

VALIDATION

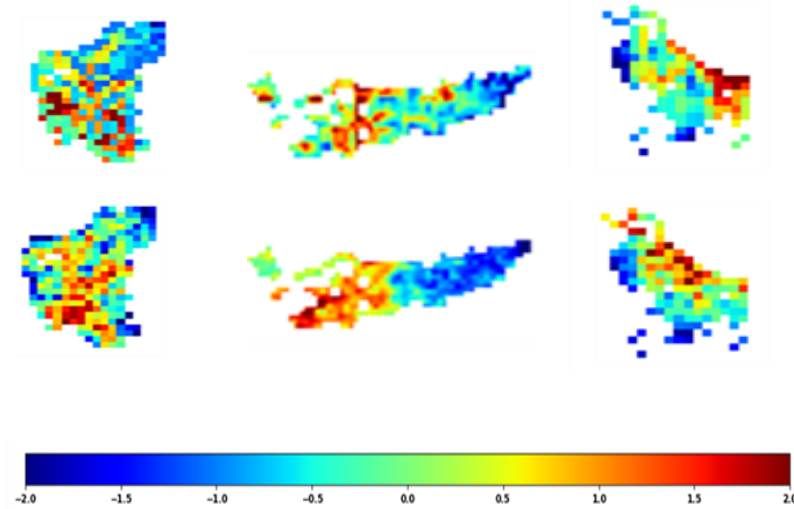
OBS



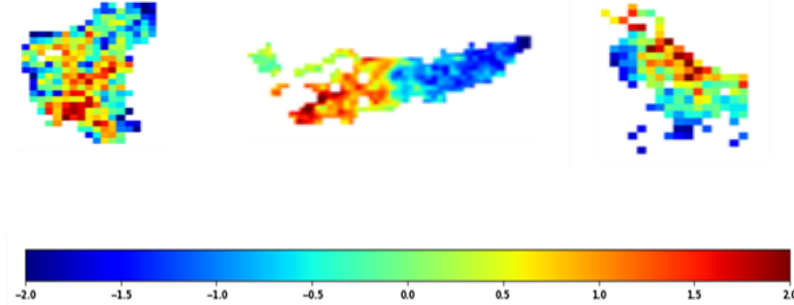
SIM



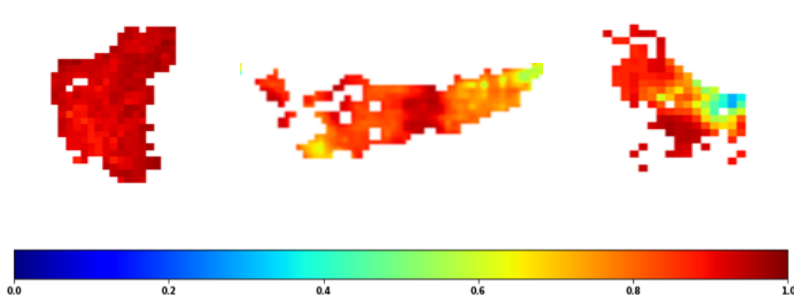
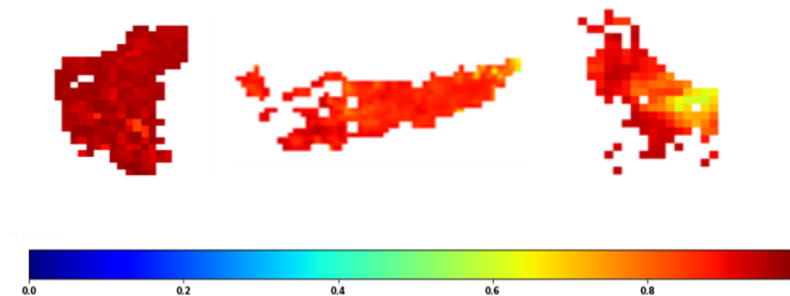
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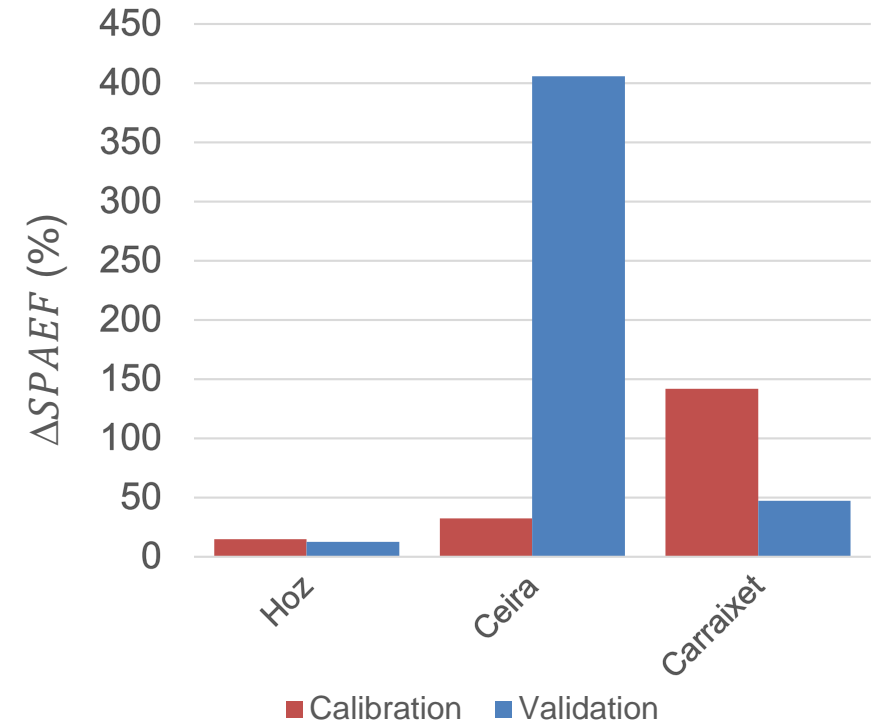
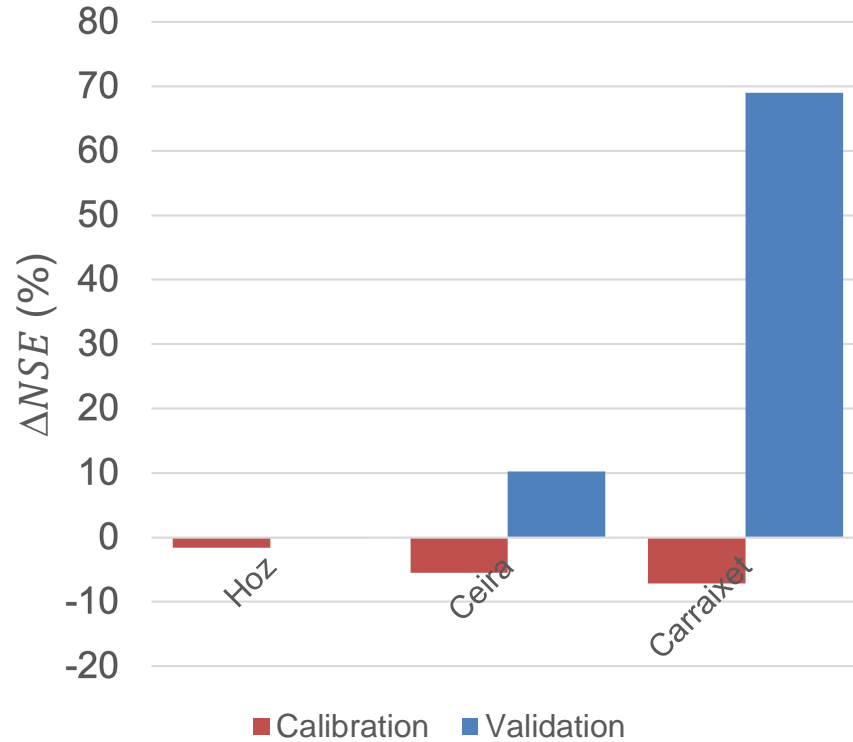
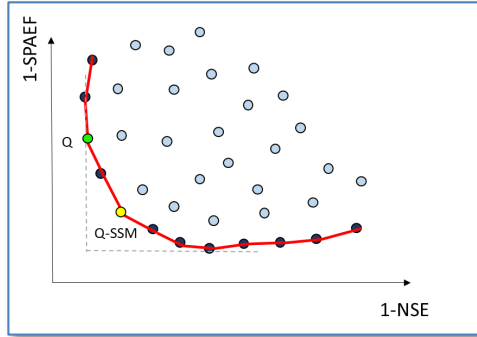


SIM



Temporal correlation

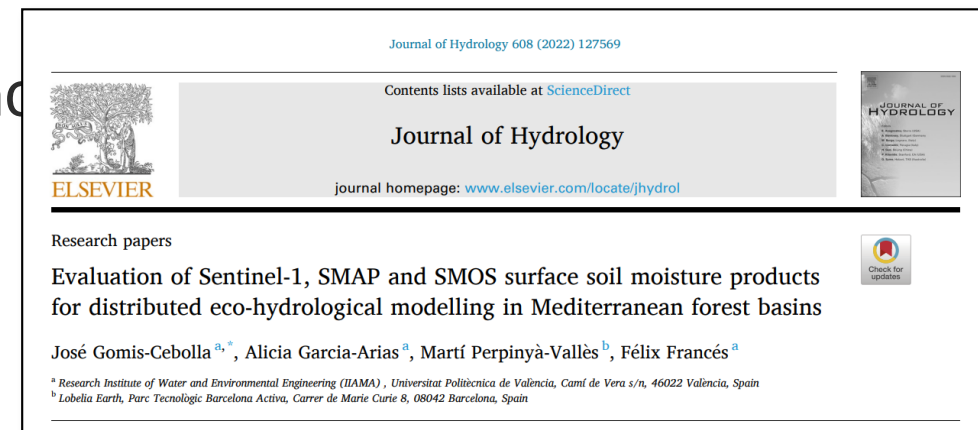




$$\Delta NSE = \frac{NSE_{Q-SSM} - NSE_Q}{NSE_Q}$$

$$\Delta SPAEF = \frac{SPAEF_{Q-SSM} - SPAEF_Q}{SPAEF_Q}$$

- ❑ We found **significant differences** in **temporal** and **spatial** dynamics of **SSM** products
- ❑ **Best** SSM products can be identified by the **spatial agreement** with **eco-hydrological modelling** estimates
 - **SMAP-Dispatch** provided the best spatial agreement with TETIS in the 3 study cases
- ❑ **Multi-objective calibration** (Q and SSM) in **eco-hydrological modelling**





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Thank you for your attention

Prof. Dr. Félix Francés (ffrances@upv.es)

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